

STEP I 2011 WORKED ANSWERS

$$\textcircled{1} \quad (i) \quad \frac{a}{x} + \frac{b}{y} = 1$$

$$- \frac{a}{x^2} - \frac{b}{y^2} \frac{dy}{dx} = 0 \Rightarrow \frac{dy}{dx} = - \frac{ay^2}{bx^2}$$

$$\begin{aligned} \text{Gradient of line \& curve same} &\Rightarrow -\frac{a}{b} = -\frac{aq^2}{bp^2} \\ \Rightarrow \frac{q^2}{p^2} &= 1 \Rightarrow p = \pm q \end{aligned}$$

$(p, q)$  on both line and curve  $\Rightarrow$

$$ap \pm bq = 1 \Rightarrow (a \pm b) = \frac{1}{p}$$

$$\frac{a}{p} \pm \frac{b}{p} = 1 \Rightarrow (a \pm b) = p$$

$$\therefore (a \pm b)^2 = 1$$

$$\text{line} \perp \text{curve} \Rightarrow -\frac{a}{b} \cdot \left( + \frac{aq^2}{bp^2} \right) = -1$$

$$\therefore \frac{a^2}{b^2} = \frac{p^2}{q^2} \Rightarrow \frac{a}{p} = \pm \frac{b}{q} \quad [1]$$

$$(p, q) \text{ on both line and curve} \Rightarrow ap + bq = 1 \quad [2]$$

$$\text{and } \frac{a}{p} + \frac{b}{q} = 1 \quad [3]$$

$$[1] + [3] \Rightarrow \frac{a}{p} = -\frac{b}{q} = \frac{1}{2}$$

$$\Rightarrow \frac{1}{p} = -\frac{b}{a}$$

$$[2] \times [3] \Rightarrow a^2 - b^2 + ab \left( \frac{1}{p} - \frac{1}{q} \right) = 1$$

$$\Rightarrow a^2 - b^2 + ab \left( \frac{a}{b} - \frac{b}{a} \right) = 1$$

$$\Rightarrow a^2 - b^2 = \frac{1}{2}$$

$$② \quad E = \int_0^1 \frac{e^x}{1+x} dx$$

$$\text{Let } I = \int_0^1 \frac{x e^x}{1+x} dx$$

$$I = \int_0^1 x e^x dx - \int_0^1 \frac{e^x}{1+x} dx$$

$$= e-1 - E$$

$$\text{Let } J = \int_0^1 \frac{x^2 e^x}{1+x} dx = \int_0^1 e^x \left( x - \frac{x}{1+x} \right) dx \\ = \int_0^1 x e^x dx - I$$

$$\int_0^1 x e^x dx = [x e^x]_0^1 - \int_0^1 e^x dx = e - (e-1) = 1$$

$$\text{So } J = 1 - I = 2 - e + E$$

$$(i) K = \int_0^1 \frac{\exp\left(\frac{1-x}{1+x}\right)}{1+x} dx$$

$$\frac{1-x}{1+x} = -1 + \frac{2}{1+x}$$

$$\text{Let } y = \frac{1-x}{1+x} \text{ and } \frac{1}{1+x} = \frac{1}{2}(y+1)$$

$$dy = -\frac{2}{(1+x)^2} dx = -(y+1) \frac{1}{(1+x)} dx$$

$$K = - \int_1^0 \exp(y) \frac{dy}{y+1} = E$$

$$\textcircled{3} \quad \sin\left(\frac{\pi}{3}-\theta\right) \sin\left(\frac{\pi}{3}+\theta\right) = \frac{1}{2} [\cos(2\theta) - \cos\frac{2\pi}{3}] \\ = -\frac{1}{2} \cos 2\theta + \frac{1}{4}$$

$$\therefore 4 \sin \theta \sin\left(\frac{\pi}{3}-\theta\right) \sin\left(\frac{\pi}{3}+\theta\right) \\ = 2 \sin \theta \cos 2\theta + \sin \theta$$

$$2 \sin \theta \cos 2\theta = \sin 3\theta - \sin \theta$$

$\therefore$  expression =  $\sin 3\theta$  as required.

Differentiating the equation and then dividing by it

$$(\cot \theta - \cot\left(\frac{\pi}{3}-\theta\right) + \cot\left(\frac{\pi}{3}+\theta\right)) = 3 \cot 3\theta$$

$$\text{Let } \theta = \frac{1}{9}\pi, \text{ then } \cot 3\theta = \frac{\cos \frac{7\pi}{3}}{\sin \frac{7\pi}{3}} = \frac{1}{\sqrt{3}}$$

$$\therefore \cot \frac{1}{9}\pi - \cot \frac{2}{9}\pi + \cot \frac{4}{9}\pi = \sqrt{3}$$

For  $\theta = \frac{\pi}{6}-\phi$  in original equation

$$\Rightarrow 4 \sin\left(\frac{\pi}{6}-\phi\right) \sin\left(\frac{\pi}{6}+\phi\right) \sin\left(\frac{\pi}{2}-\phi\right) = \sin\left(\frac{\pi}{2}-3\phi\right)$$

$$\Rightarrow 4 \cos\left(\frac{\pi}{3}+\phi\right) \cos\left(\frac{\pi}{3}-\phi\right) \cos \phi = \cos 3\phi$$

Put  $\phi = \theta$  and divide by original equation

$$\cot \theta \cot\left(\frac{\pi}{3}-\theta\right) \cot\left(\frac{\pi}{3}+\theta\right) = \cot 3\theta$$

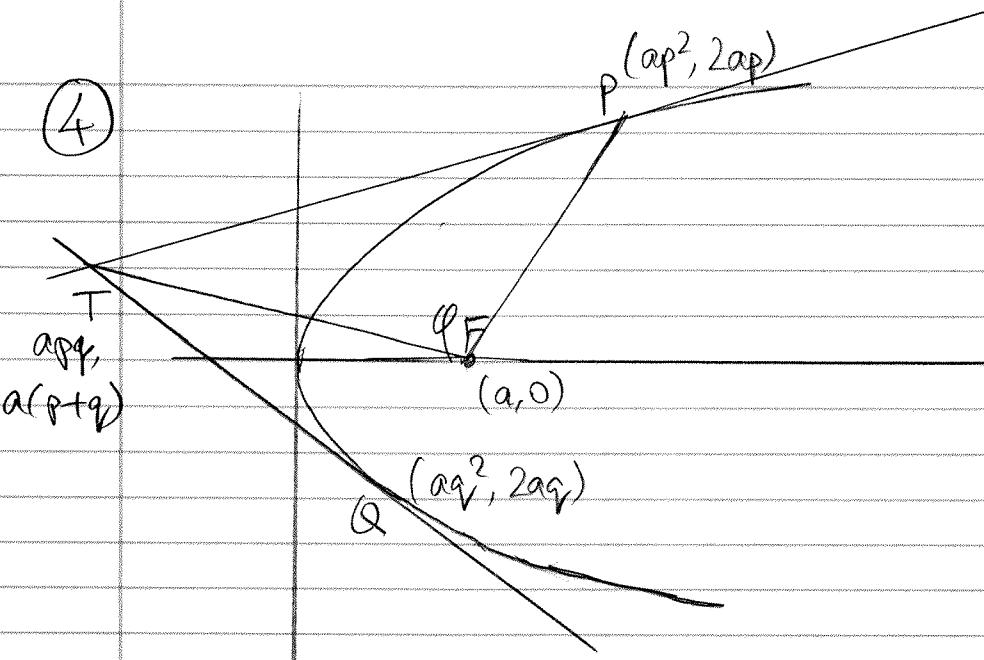
Differentiating this equation and then dividing by it and

$$\text{noting } -\frac{\operatorname{cosec}^2 \theta}{\cot \theta} = -\frac{1/\sin 2\theta}{\cos \theta / \sin \theta} = -\frac{1}{\sin \theta \cos \theta} = -\frac{1}{2} \operatorname{cosec} 2\theta$$

$$\operatorname{cosec} 2\theta - \operatorname{cosec}\left(\frac{2\pi}{3}-2\theta\right) + \operatorname{cosec}\left(\frac{2\pi}{3}+2\theta\right) = 3 \operatorname{cosec} 6\theta$$

$$\text{Put } \theta = \frac{\pi}{18}$$

$$\operatorname{cosec} \frac{\pi}{9} - \operatorname{cosec} \frac{5\pi}{9} + \operatorname{cosec} \frac{7\pi}{9} = \frac{3}{\sin \frac{\pi}{3}} = 2\sqrt{3}$$



At general point  $y = 2at$   $\Rightarrow \frac{dy}{dt} = 2a$   
 $x = at^2$   $\Rightarrow \frac{dx}{dt} = 2at$

$$\Rightarrow \frac{dy}{dx} = \frac{1}{t}$$

∴ Target is  $(y - 2at) = \frac{1}{t}(x - at^2)$

As for meeting point of targets at P and Q

$$y - 2ap = \frac{1}{p}(x - a^2) \quad [1]$$

$$y - 2aq = \frac{1}{q}(x - a^2) \quad [2]$$

$$[1] - [2] \Rightarrow 2a(q-p) = \left(\frac{q-p}{pq}\right)x + a(q-p)$$

$$x = app$$

$$p[1] - q[2] \Rightarrow (p-q)y - 2a(p^2 - q^2) = -a(p^2 - q^2)$$

$$\therefore y = a(p+q)$$

Cosine rule in triangle TFP, eliminating  $a^2$  factor

$$(p^2 - pq)^2 + (p - q)^2 = (p^2 - 1)^2 + 4p^2 + (pq - 1)^2 + (p + q)^2$$

$$- 2 \cos \varphi \sqrt{(p^2 - 1)^2 + 4p^2)((pq - 1)^2 + (p + q)^2)}$$

$$(p - q)^2(p^2 + 1) = (p^2 + 1)^2 + p^2q^2 + p^2 + q^2 + 1$$

$$- 2 \cos \varphi (p^2 + 1) \sqrt{(p^2 + 1)(q^2 + 1)}$$

④ contd

$$(1-q)^2 = p^2 + 1 + q^2 + 1 - 2\cos \rho \sqrt{(p^2+1)(q^2+1)}$$

$$\therefore \cos \rho = \frac{pq+1}{\sqrt{(p^2+1)(q^2+1)}}$$

Since this is symmetrical in  $p$  and  $q$ , and  $\overset{\wedge}{TFP}$  and  $\overset{\wedge}{TFQ}$  are both between  $O$  and it

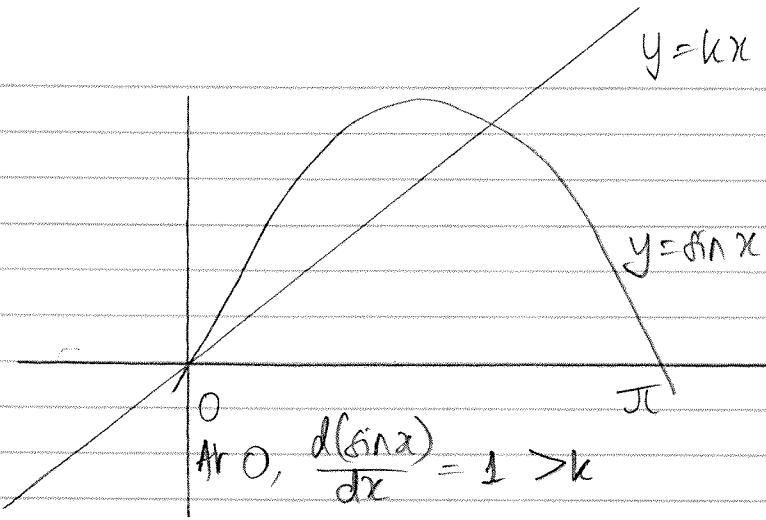
$$\overset{\wedge}{TFP} = \overset{\wedge}{TFQ}$$

$\therefore \overset{\wedge}{TF}$  bisects  $\overset{\wedge}{PFQ}$

This can also be proved more neatly by geometry

bit. by parabola?

5



As long as  $k < 1$ ,  $y = kx$  is below  $y = \sin x$  for some range in  $0 < x < \pi$   
As long as  $k > 0$ ,  $y = kx$  is above  $y = \sin x$  for some range in  $0 < x < \pi$

Slope of  $y = \sin x$  monotone decreasing for  $0 < x < \pi$

$\therefore$  after first intersection slope of  $y = \sin x < k$ ,

$\therefore$  no second intersection can follow for  $0 < x < \pi$ .

$$\begin{aligned} I &= \int_0^\alpha (\sin x - kx) dx + \int_\alpha^\pi (kx - \sin x) dx \\ &= \left[ -\cos x - \frac{1}{2}kx^2 \right]_0^\alpha + \left[ \cos x + \frac{1}{2}kx^2 \right]_\alpha^\pi \\ &= -\cos \alpha - \frac{1}{2}k\alpha^2 - \cos 0 - \frac{1}{2}k\alpha^2 \\ &\quad + 1 - 1 + \frac{1}{2}k\pi^2 \\ &= \frac{1}{2}k\pi^2 - 2 \cos \alpha - k\alpha^2 \end{aligned}$$

Substituting  $k = \frac{\sin \alpha}{\alpha}$

$$I = \frac{\pi^2 \sin \alpha}{2\alpha} - \alpha \sin \alpha - 2 \cos \alpha$$

⑤

contd

$$\begin{aligned}\frac{d\Gamma}{d\alpha} &= \frac{\pi^2 \cos \alpha}{2\alpha} - \frac{\pi^2 \sin \alpha}{2\alpha^2} - \sin \alpha - \alpha \cos \alpha + 2 \sin \alpha \\ &= \left( \frac{\pi^2}{2\alpha^2} - 1 \right) (\alpha \cos \alpha - \sin \alpha)\end{aligned}$$

∴  $\frac{d\Gamma}{d\alpha} = 0$  when  $\tan \alpha = \alpha$  (but, by inspecting the graph, that's never true)

or when  $\frac{\pi^2}{2\alpha^2} = 1$

$$\text{i.e. } \alpha = \frac{\pi}{\sqrt{2}}$$

$$\begin{aligned}\text{At } \alpha = \frac{\pi}{\sqrt{2}}, \quad \Gamma &= \frac{\pi^2 \sin \left( \frac{\pi}{\sqrt{2}} \right)}{\pi \sqrt{2}} - \frac{\pi}{\sqrt{2}} \sin \frac{\pi}{\sqrt{2}} - 2 \cos \frac{\pi}{\sqrt{2}} \\ &= -2 \cos \frac{\pi}{\sqrt{2}}\end{aligned}$$

When  $\alpha$  is almost 0,  $\Gamma$  is almost 2

when  $\alpha$  is almost 1,  $\Gamma$  is almost  $\frac{1}{2}\pi^2 - 2 > 2$

∴ on both sides  $\Gamma > -2 \cos \frac{\pi}{\sqrt{2}}$

∴  $-2 \cos \frac{\pi}{\sqrt{2}}$  is minimum value of  $\Gamma$ .

$$⑥ \text{ Coefft of } x^r = \frac{-3, -4, -5, \dots (-r-2) (-1)^r}{1, 2, 3, \dots r}$$

$$= \frac{1}{2} (r+1)(r+2)$$

Coefft of  $x^r$  in expansion of  $(1-x+2x^2)(1-x)^{-3}$

$$= \text{coefft of } x^r - \text{coefft of } x^{r-1} + 2 \times \text{coefft of } x^{r-2}$$

$$= \frac{1}{2}(r+1)(r+2) - \frac{1}{2} r(r+1) + (r-1)r$$

$$= r^2 + 1$$

$$\text{Series} = 1 + \frac{1^2 + 1}{2} + \frac{2^2 + 1}{4} + \frac{3^2 + 1}{8} + \frac{4^2 + 1}{16} + \dots \\ \dots + \frac{r^2 + 1}{2^r} + \dots$$

$$= \frac{1-x+2x^2}{(1-x)^3} \text{ when } x = \frac{1}{2}$$

$$= \frac{1-\frac{1}{2}+\frac{1}{2}}{\frac{1}{8}} = 8$$

$$(ii) \text{ Cited series} = 1 + \frac{2^2}{2} + \frac{3^2}{4} + \frac{4^2}{8} + \frac{5^2}{16} + \frac{6^2}{32} + \frac{7^2}{64} + \dots$$

$$= 2 \left( 1 + \frac{1^2 + 1}{2} + \frac{2^2 + 1}{4} + \frac{3^2 + 1}{8} + \dots \right)$$

$$- 2 \left( 1 + \frac{1}{2} + \frac{1}{4} + \frac{1}{8} + \dots \right)$$

$$= 16 - 4 = 12$$

7

Assume to reduce clutter that  
cross-section = 1

$\int A$

then  $\frac{dh}{dt} = A - \lambda h$  for some  
const  $\lambda > 0$

If  $\frac{dh}{dt} = 0$  when  $h = \alpha^2 H$

then  $A = \lambda \alpha^2 H$

$\downarrow \lambda h$

and  $\frac{dh}{dt} = \lambda (\alpha^2 H - h)$

Let  $\eta = \frac{h}{\alpha^2 H}$ , then  $\frac{d\eta}{dt} = \lambda(1 - \eta)$

so  $-\ln(1 - \eta) = At + \text{const.}$

$h = H$ , so  $\eta = \frac{1}{\alpha^2}$ , when  $t = 0 \Rightarrow \text{const} = -\ln(1 - \frac{1}{\alpha^2})$

When  $h = \alpha H$ , or  $\eta = \frac{1}{\alpha}$

$$-\ln(1 - \frac{1}{\alpha}) = At - \ln(1 - \frac{1}{\alpha^2})$$

$$\therefore At = \ln(1 + \frac{1}{\alpha})$$

for large  $\alpha$ ,  $\ln(1 + \frac{1}{\alpha}) \approx \frac{1}{\alpha}$

$$\therefore At \approx \frac{1}{\alpha}$$

⑦ contd

Under the new conditions

$$\frac{dh}{dt} = \lambda (\sqrt{\alpha H} - \sqrt{h}) \quad \text{for a new constant } \lambda$$

$$\text{Let } \frac{h}{\alpha^{1/2}} = \eta$$

$$\text{Then } \alpha^{1/2} \frac{d\eta}{dt} = \lambda (1 - \sqrt{\eta})$$

$$\frac{d\eta}{1-\eta^2} = \frac{\lambda}{\alpha^{1/2}}$$

$$\text{Let } y = \eta^{1/2}, \text{ so } y^2 = \eta, \text{ and } 2y \, dy = d\eta$$

$$\frac{2y \, dy}{1-y} = \frac{\lambda}{\alpha^{1/2}}$$

$$\left( -2 + \frac{2}{1-y} \right) dy = \frac{\lambda}{\alpha^{1/2}}$$

$$-2y - 2 \ln(1-y) = \frac{\lambda t}{\alpha^{1/2}} + \text{const.}$$

$$\text{Since } h=H, \text{ so } \eta = \frac{1}{\alpha^{1/2}} \text{ and } y = \frac{1}{\alpha} \text{ when } t=0$$

$$\text{const} = -\frac{2}{\alpha} - 2 \ln\left(1 - \frac{1}{\alpha}\right)$$

$$\text{We want } t \text{ for } h=\alpha H, \text{ i.e. } \eta = \frac{1}{\alpha}, y = \frac{1}{\sqrt{\alpha}}$$

$$\frac{\lambda t}{\alpha^{1/2}} - \frac{2}{\alpha} - 2 \ln\left(1 - \frac{1}{\alpha}\right) = -\frac{2}{\sqrt{\alpha}} - 2 \ln\left(1 - \frac{1}{\sqrt{\alpha}}\right)$$

$$\frac{\lambda t}{\alpha^{1/2}} = 2 \ln\left(1 + \frac{1}{\sqrt{\alpha}}\right) + \frac{2}{\alpha} - \frac{2}{\sqrt{\alpha}}$$

$$\therefore \lambda t = 2\sqrt{\alpha} \left(1 - \sqrt{\alpha} + \alpha \ln\left(1 + \frac{1}{\sqrt{\alpha}}\right)\right)$$

(7)

contd

$\sqrt{H} \propto \alpha$  is large

$$\ln(1 + \frac{1}{\sqrt{\alpha}}) \approx \frac{1}{\sqrt{\alpha}} - \frac{1}{2\alpha}$$

$$\therefore At \approx 2\sqrt{H} \left( 1 - \sqrt{\alpha} + \sqrt{\alpha} - \frac{1}{2} \right) \approx \sqrt{H}$$

$$⑧ (i) M^3 = n^3 + n^2 + 1 \quad (*)$$

for all  $n$ ,  $n^2 \geq 0 \therefore M^3 > n^3$

Since cubic is monotone increasing,  $M > n$ .

$$M < (n+1) \iff M^3 < (n+1)^3 = n^3 + 3n^2 + 3n + 1$$

$$\iff n^3 + n^2 + 1 < n^3 + 3n^2 + 3n + 1$$

$$\iff 0 < 2n^2 + 3n$$

$$2n^2 + 3n = 2n(n + \frac{3}{2}), \text{ so is positive if } n < -\frac{3}{2}$$

or if  $n > 0$

$\therefore$  for all values of  $n$  outside  $-\frac{3}{2} \leq n \leq 0$

$$n < M < n+1$$

$\therefore$  if  $(*)$  is true and  $m$  and  $n$  are integers

Either  $n = -1$ , and then  $M = 1$

Or  $n = 0$ , and then  $M = 1$  again

or  $n < M < n+1$ , which is impossible if  $m$  and  $n$  are integers.

$$(ii) (\dagger) p^3 = q^3 + 2q^2 - 1 \Rightarrow q = 0 \text{ (and } p = -1)$$

$$\text{or } p > q$$

$$(\dagger) \text{ also } \Rightarrow p^3 = (q+1)^3 - q^2 - 3q - 2$$

$$= (q+1)^3 - (q+2)(q+1)$$

$\therefore$  if  $q = -1$ ,  $p = 0$ . If  $q = -2$ ,  $p = -1$

otherwise if  $q > -1$ ,  $p^3 < (q+1)^3$ , so  $q < p < q+1$

which is impossible for integer  $p, q$ . And if  $q < -2$ , ditto.

$\therefore$  only solutions are  $p = 0, q = -1$

$$p = -1, q = -2$$

$$p = -1, q = 0$$

**STEP I/2011/9**

The trajectory is  $y = Bx - Ax^2$  for some B, A

Since  $\frac{dy}{dx} = \tan\theta$  at  $x = 0$ ,  $B = \tan\theta$ , and so

$$d_2 = \tan\theta d_1 - Ad_1^2 \quad [1]$$

$$d_1 = \tan\theta d_2 - Ad_2^2 \quad [2]$$

Eliminating A,  $d_2^3 - \tan\theta d_1 d_2^2 = d_1^3 - \tan\theta d_1^2 d_2$

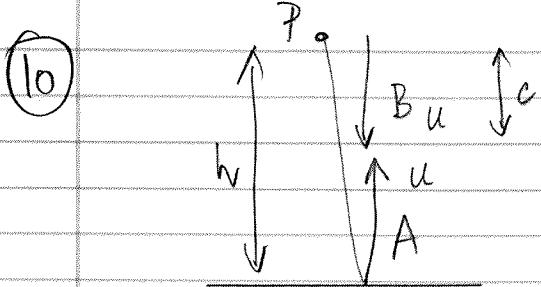
$$\text{So } \tan\theta = \frac{d_1^2 + d_1 d_2 + d_2^2}{d_1 d_2}$$

$$\text{Range} = \frac{\tan\theta}{A}$$

$$[1] \text{ and } [2] \implies A = \frac{(d_1 - d_2)(\tan\theta + 1)}{d_1^2 - d_2^2} = \frac{\tan\theta + 1}{d_1 + d_2}$$

$$\tan\theta + 1 = \frac{(d_1 + d_2)^2}{d_1 d_2}, \text{ so } A = \frac{d_1 + d_2}{d_1 d_2}$$

$$\text{Range} = \frac{\tan\theta}{A} = \frac{d_1^2 + d_1 d_2 + d_2^2}{d_1 + d_2}$$



If the bounce on the plane is perfectly elastic, then the speed of A at any height bouncing back up = its speed when dropping down at the same height.  
= Speed of B at that height.

After first collision, let speeds of A and B be  $v_A$  and  $v_B$  upwards

$$\text{Then } Mv_u - mv_u = Mv_A + mv_B \quad [1]$$

$$2u = v_B - v_A \quad [2]$$

$$[1] - m[2] \Rightarrow Mv_u - 3mv_u = (M+m)v_A$$

If  $M > 3m$ , then LHS of this equation  $> 0$

$\therefore \text{RHS} > 0$   
 $\therefore v_A > 0$  and both particles move up.

Ball will rise above height  $h$  after the first collision by  $\frac{v_B^2 - u^2}{2g}$ , i.e. by an amount proportional to its gain in KE from the collision.

Elastic collision  $\Rightarrow v_A = v_B - 2u$

Conservation of momentum  $\Rightarrow Mv_A + mv_B = (M-m)u$

$$\Rightarrow (M+m)v_B - 2Mu = (M-m)u$$

$$\Rightarrow (M+m)(v_B - u) = 2(M-m)u$$

$$\Rightarrow (M+m)(v_B + u) = 4Mu$$

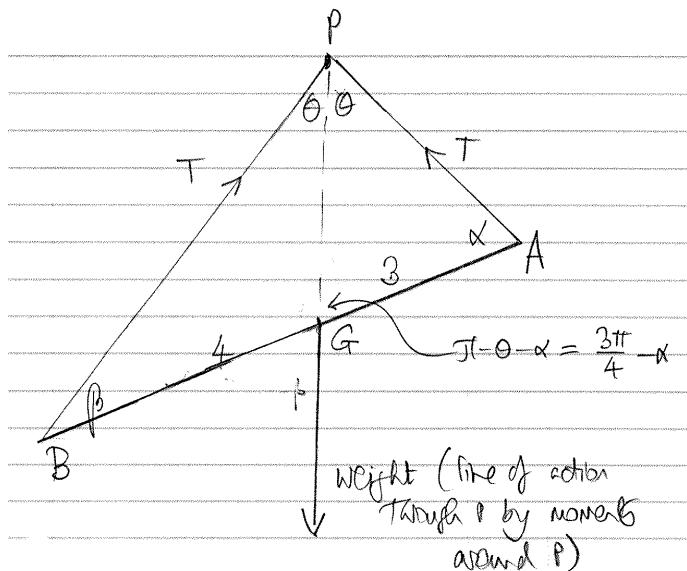
$$\text{Multiply, } (M+m)^2(v_B^2 - u^2) = 8M(M-m)u^2$$

Therefore B rises  $\frac{4M(M-m)u^2}{(M+m)^2 g}$  above height  $h$ .

# STEP 1 2011 Q.11

Martin Thomas

May 27, 2017



Peg smooth  $\Rightarrow$  tension  $T$  is the same on both parts of the string, otherwise the string would slip on the peg.

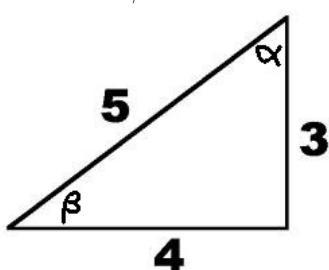
Moments around P  $\Rightarrow$  G is vertically below P, so that the line of action of the weight passes through P, otherwise the rod would rotate around P

Resolving forces horizontally  $\Rightarrow$  the two angles marked  $\theta$  are equal, or else the rod would move sideways

Moments around G  $\Rightarrow$   $4 \sin \beta = 3 \sin \alpha$

$$\cos \beta = \frac{4}{5} \Rightarrow \sin \beta = \frac{3}{5} \Rightarrow \sin \alpha = \frac{4}{5}$$

So  $\alpha$  and  $\beta$  are as shown below, and  $2\theta = \frac{\pi}{2}$



In the right-angle triangle BPA,  $AP = 7 \sin \beta$  and  $BP = 7 \sin \alpha$

$$\text{So } AP = \frac{21}{5}, \text{ } BP = \frac{28}{5}, \text{ length of string} = \frac{49}{5}$$

$$\text{Angle between rod and horizontal} = \frac{\pi}{2} - (\frac{3\pi}{4} - \alpha) = \alpha - \frac{\pi}{4}$$

$$\text{so } \tan(\text{angle}) = \frac{\tan \alpha - \tan \frac{\pi}{4}}{1 + \tan \alpha \tan \frac{\pi}{4}} = \frac{\frac{4}{3} - 1}{1 + \frac{4}{3}} = \frac{1}{7}$$

(12) (i) If  $n=1$ , then I'm food unless the L2 person comes first, which has  $P = \frac{n}{n+m} = \frac{1}{m+1}$

$$\therefore P(\text{good}) = \frac{m}{m+1}$$

(ii) Let 0 represent A2 coin, 1 represent L1. Options for first three are

0	0	0	X
0	0	1	X
0	1	0	X
0	1	1	X
1	0	0	X
1	0	1	✓
1	1	0	✓
1	1	1	✓

$$P = \frac{m}{m+2} \cdot \frac{2}{m+1} \cdot \frac{m-1}{m}$$

$$P = \frac{m}{m+2} \cdot \frac{m-1}{m+1} \cdot \frac{2}{m}$$

$$P = \frac{m}{m+2} \cdot \frac{m-1}{m+1} \cdot \frac{m-2}{m}$$

X denotes no food, ✓ denotes food

$$\text{Total } P(\text{good}) = \frac{2m^2 - 2m + 2m^2 - 2m + m^3 - 3m^2 + 2m}{m(m+1)(m+2)}$$

$$= \frac{m^3 + m^2 - 2m}{m(m+1)(m+2)} = \frac{(m+2)(m-1)m}{m(m+1)(m+2)} = \frac{m-1}{m+1}$$

Options for first four with  $n=3$

Starts 0  $\Rightarrow$  no good

Starts 10  $\Rightarrow$  2-case with  $n \mapsto n-1$

$$P(\text{good}) = \frac{m-2}{m} \quad P(\text{case}) = \frac{m}{m+3}, \frac{3}{m+2}$$

Starts 1100  $\Rightarrow$  1-case with  $m \mapsto m-2$

$$P(\text{good}) = \frac{m-2}{m-1} \quad P(\text{case}) = \frac{m}{m+3}, \frac{m-1}{m+2}, \frac{3}{m+1}, \frac{2}{m}$$

Starts 1101  $\Rightarrow$  good

$$P(\text{case}) = \frac{m}{m+3}, \frac{m-1}{m+2}, \frac{3}{m+1}, \frac{m-2}{m}$$

Starts 111  $\Rightarrow$  good

$$P(\text{case}) = \frac{m}{m+3}, \frac{m-1}{m+2}, \frac{m-2}{m+1}$$

Total  $P(\text{good}) =$

$$\frac{m-2}{m} \cdot \frac{m}{m+3} \cdot \frac{3}{m+2} + \frac{m-2}{m-1} \cdot \frac{m}{m+3} \cdot \frac{m-1}{m+2} \cdot \frac{3}{m+1} \cdot \frac{2}{m}$$

$$+ \frac{3}{m} \cdot \frac{m}{m+3} \cdot \frac{m-1}{m+2} \cdot \frac{m-2}{m+1} + \frac{m}{m+3} \cdot \frac{m-1}{m+2} \cdot \frac{m-2}{m+1}$$

$$= \frac{m-2}{m+1} \cdot \frac{1}{(m+2)(m+3)} \cdot (3m+3 + 6 + 3m-3 + m^2 - m)$$

$$= \frac{m-2}{m+1} \cdot \frac{1}{(m+2)(m+3)} (m^2 + 5m + 6) = \frac{m-2}{m+1}$$

(13)

By definition

$$1 = \int_{-a}^0 2kdx + \int_0^2 k\sqrt{4-x^2} dx$$

$$= 2ak + k \left[ 2\sin^{-1}\left(\frac{1}{2}x\right) + \frac{1}{2}x\sqrt{4-x^2} \right]_0^2 \\ = 2ak + k\pi$$

$$\therefore k = \frac{1}{2a+\pi}$$

$$\text{mean}(x) = \int_{-a}^0 2kx dx + \int_0^2 kx\sqrt{4-x^2} dx \\ = \left[ kx^2 \right]_a^0 + \left[ -\frac{k}{3}(4-x^2)^{3/2} \right]_0^2 \\ = -ka^2 + \frac{8k}{3} \\ = \frac{8-3a^2}{3(2a+\pi)}$$

$$\text{By above } P(X>0) = \frac{\pi}{2a+\pi} \quad (\text{2nd integral})$$

$$P(X>0) > \frac{1}{10} \Leftrightarrow \frac{\pi}{2a+\pi} < \frac{1}{10} \leq 9\pi < 2a$$

$$\therefore 2a > 9\pi \Rightarrow a < 0$$

$$\therefore P(X < d) = 2k(d+a) = \frac{9}{10}$$

$$\therefore d = \frac{9}{20k} - a = \frac{9\pi - 2a}{20}$$

(13)

contd.

$$d = \sqrt{2} \Rightarrow \int_{\sqrt{2}}^2 k \sqrt{4-x^2} dx = \frac{1}{10}$$

$$\Rightarrow k \left[ 2 \sin^{-1} \left( \frac{1}{2}x \right) + \frac{1}{2} x \sqrt{4-x^2} \right]_{\sqrt{2}}^2 = \frac{1}{10}$$

$$\Rightarrow k \left[ \pi - \frac{\pi}{2} - 1 \right] = \frac{1}{10}$$

$$\Rightarrow 5\pi - 10 = 2a + \pi$$

$$\Rightarrow a = 2\pi - 5$$

**STEP I/2011/9**

The trajectory is  $y = Bx - Ax^2$  for some B, A

Since  $\frac{dy}{dx} = \tan\theta$  at  $x = 0$ ,  $B = \tan\theta$ , and so

$$d_2 = \tan\theta d_1 - Ad_1^2 \quad [1]$$

$$d_1 = \tan\theta d_2 - Ad_2^2 \quad [2]$$

Eliminating A,  $d_2^3 - \tan\theta d_1 d_2^2 = d_1^3 - \tan\theta d_1^2 d_2$

$$\text{So } \tan\theta = \frac{d_1^2 + d_1 d_2 + d_2^2}{d_1 d_2}$$

$$\text{Range} = \frac{\tan\theta}{A}$$

$$[1] \text{ and } [2] \implies A = \frac{(d_1 - d_2)(\tan\theta + 1)}{d_1^2 - d_2^2} = \frac{\tan\theta + 1}{d_1 + d_2}$$

$$\tan\theta + 1 = \frac{(d_1 + d_2)^2}{d_1 d_2}, \text{ so } A = \frac{d_1 + d_2}{d_1 d_2}$$

$$\text{Range} = \frac{\tan\theta}{A} = \frac{d_1^2 + d_1 d_2 + d_2^2}{d_1 + d_2}$$